PERiLS Year 2 ULM Doppler Wind LiDAR (DWL) + Sounding Data Update

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Halo Photonics Streamline XR DWL

- Instrument Info
 - 18-m range gate spacing; Doppler bandwidth ± 19 m s⁻¹
 - First useable gate near 40-m AGL; Z_{MAX} depends on aerosol load, cloud base height, and precipitation.
 - DWL provides near instantaneous observations of the wind field
- Operation strategy
 - Fixed location for IOP duration beginning 4-hours before T-0; coordinated with other profiler PIs
 - 8-pt az VAD scans at 70° el every 5-min with continuous vertical stares in between
 - Care taken to ensure DWL was level and correct heading recorded in operating software
- QC underway
 - Final datasets will be netCDF (*.stare.nc and *.VAD.nc)
 - All files will include *epoch time, hours* (since 00 UTC on day), *lat, lon, alt, SNR, height* (AGL above DWL)
 - Stare files will include *w* (m s⁻¹; vertical velocity) & *attenuated backscatter* (m⁻¹ sr⁻¹)
 - VAD files will include u, v, w (as retrieved from VAD technique), horizontal wind speed, horizontal wind direction, RMS (m s⁻¹; root mean square error of derived radial velocity compared to observed radial velocity) & R² (coefficient of determination comparing derived radial velocity to observed radial velocity; gives measure of wind field homogeneity)

iMet-4-AB 403 MHz sondes

- Operation strategy
 - 60-90 min radiosonde launches at fixed DWL location coordinated with other profiling teams typically beginning 4 hours prior to T-0
 - Launch frequency typically increased as convection approached but launches became less coordinated between teams
 - Balloons filled to target median ascent rates 3-5 m s⁻¹
- QC complete; need to upload data
 - Similar to year 1 process
 - Automatic processing of raw sonde data by iMetOS-II software; resampled to 5-s resolution
 - QC for inconsistent heights, temp/dew, and wind data. Data removed if balloon was descending.
 - 3 CSV text files for each launch (primary format, SPC/SHARPPy format, and flight summary)
 - Primary format gives launch date/time, location, and elevation in header with: lat, lon, UTC time, height, pressure, temp, RH, dew, wind speed, wind direction, & ascent rate

iMet-4-AB 403 MHz sondes

- iMet-4 sondes tend to exhibit a low RH bias relative to surrounding surface data in some instances.
- This has been examined in detail; bias is not systematic, but for some sondes dew points were 2-4°C lower than known calibrated sensors
- Low bias was always within the uncertainty (5%) of the iMet RH sensor
- During QC sonde data compared to surrounding surface datasets. Only a few flights had large discrepancies in surface dew points. These were adjusted by increasing the RH (≤ 5%) to better align with surrounding datasets.

Summary

YEAR 1	IOP	IOP1		IOP2		IOP3		P4	Total
DWL hours	9	9		7.5		7		.5	29
Soundings	8	8		9		7		7	31
YEAR 2	IOP1	IC	OP2	IOF	9 3	IOP4		IOP5	Total
DWL hours	12.8		10	9.	3	10.7		6.4	49.2
Soundings	9		8	8		9		6	40

- With the exception of IOP4, both sonde and DWL data (including VAD retrievals) are good to excellent quality.
- IOP4 (TN Valley) exhibited persistent signal quality issues with the sondes and lower quality DWL data; VAD retrievals are of poorer quality compared to the other IOPs – needs to be fully investigated
- iMet sondes have transmission issues when lightning is nearby
 - Only an issue for a handful of sondes in year 2

